

Exercise 1: Let  $T \neq \text{id}$  be a translation.

Prove that the only invariant lines of  $T$  are those parallel to the translation vector  $v$ .

Let  $\ell$  be a line

Choose a representation  $\overleftrightarrow{AB}$  of  $\vec{v}$  where  $A, B \notin \ell$ ;  $B = T(A)$ .

Take,  $P \in \ell$ . We know  $A, P, T(P), B$  is a parallelogram (or a single line segment), so  $\overleftrightarrow{AB} \parallel \overleftrightarrow{PT(P)}$ .

" $\Rightarrow$ " assume  $\ell$  is invariant

then  $T(P) \in \ell$ , so  $\overleftrightarrow{PT(P)} = \ell$ .

so  $\ell$  is parallel to  $\overleftrightarrow{AB}$  and hence to  $\vec{v}$ .

" $\Leftarrow$ " assume  $\ell$  is parallel to  $\vec{v}$  and hence to  $\overleftrightarrow{AB}$ .

Since  $\overleftrightarrow{PT(P)}$  is also parallel to  $\overleftrightarrow{AB}$  and passes through  $P$ ,

Playfair's Postulate implies  $\overleftrightarrow{PT(P)} = \ell$ .

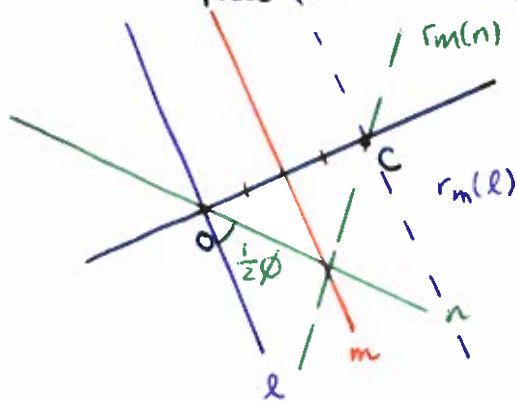
so  $T(P) \in \ell$ .

since  $P \in \ell$  was arbitrary, we see that  $T(\ell) \subset \ell$ .  $\square$

Exercise 2: (a) Suppose we are given a coordinate system with origin  $O$ .

Let  $\text{Rot}_\phi$ ; let  $C = (x, y) \neq O$  and let  $T(a, b) = (a, b) + (x, y)$ .

Prove that  $T \circ \text{Rot}_\phi \circ T^{-1}$  is a rotation about  $C$  by  $\phi$ .



Let  $\ell$  be the line through  $O$  perpendicular to  $\overleftrightarrow{OC}$ .

Let  $m$  be the perpendicular bisector of  $\overleftrightarrow{OC}$ .

Let  $n$  be the angle bisector of the angle made by  $\ell$  and  $\text{Rot}_\phi(\ell)$ .

So  $T = r_m \circ r_\ell$ ,  $T^{-1} = r_\ell \circ r_m$ ,  $\text{Rot}_\phi = r_n \circ r_\ell$

So  $T \circ \text{Rot}_\phi \circ T^{-1} = (r_m \circ r_\ell) \circ (r_n \circ r_\ell) \circ (r_\ell \circ r_m)$

$= r_m \circ r_\ell \circ r_n \circ r_m$

$= r_m \circ r_\ell \circ r_m \circ r_m \circ r_n \circ r_m$

$= r_{r_m(\ell)} \circ r_{r_m(n)}$

(ii)

(i)

$l$  and  $n$  intersect at  $O$  with angle  $\phi/2$

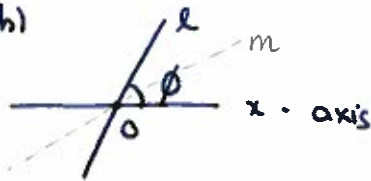
$\Rightarrow r_m(l)$  and  $r_m(n)$  intersect at  $r_m(O) = C$  with angle  $\phi/2$ .

$$\Rightarrow r_m(l) \circ r_m(n) = \text{Rot}_{C, 2(\phi/2)} = \text{Rot}_{C, \phi}$$

(Note that the orientation matches - it's not  $-\phi$ )

(iii)

(h)



Claim:  $r_l = \text{Rot}_\phi \circ r_x \circ \text{Rot}_{-\phi}$

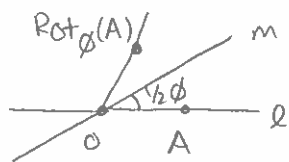
Let  $m$  be the angle bisector of the angle made by  $x$ -axis and  $l$ , so  $\text{Rot}_\phi = r_m \circ r_x$ .

$$\begin{aligned} \Rightarrow \text{Rot}_\phi \circ r_x \circ \text{Rot}_{-\phi} &= (r_m \circ r_x) \circ r_x \circ (r_x \circ r_m) \\ &= r_m \circ r_x \circ r_m \\ &= r_m, \quad \text{where } m = r_m(x\text{-axis}) \\ &= l. \end{aligned}$$

Exercise 2:

(a) prove that  $(\text{Rot}_\phi)^{-1} = \text{Rot}_{-\phi}$ , using reflections.

Choose a point  $A \neq O$ ; let  $l = \overleftrightarrow{OA}$  and let  $m$  be the angle bisector of  $\angle A O \text{Rot}_\phi(A)$ .

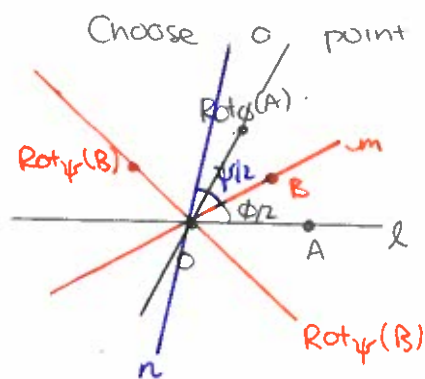


$$\text{So } \text{Rot}_\phi = r_m \circ r_l$$

$$\begin{aligned} \Rightarrow (\text{Rot}_\phi)^{-1} &= r_l \circ r_m, \quad \text{which is rotation} \\ &\text{about } O = l \cap m \text{ by angle} \\ &2(\text{angle from } m \text{ to } l) \\ &= 2(-\frac{1}{2}\phi) = -\phi. \end{aligned}$$

$$\Rightarrow (\text{Rot}_\phi)^{-1} = \text{Rot}_{-\phi}$$

(b). Prove that  $\text{Rot}_\psi \circ \text{Rot}_\phi = \text{Rot}_\theta$  is again a rotation, using reflections.



Choose a point  $A \neq O$  and let  $l = OA$ .

Let  $m$  be the angle bisector of  $\angle AORot_\phi(A)$ .

Let  $B$  be a point on  $m$  not equal to  $O$ .

Let  $n$  be the angle bisector of  $\angle BORot_\psi(B)$ .

$\Rightarrow \text{Rot}_\phi = r_m \circ r_l$ , and  $m$  and  $l$  form angle  $\frac{1}{2}\phi$

$\text{Rot}_\psi = r_n \circ r_m$  and  $n$  and  $m$  form angle  $\frac{1}{2}\psi$ .

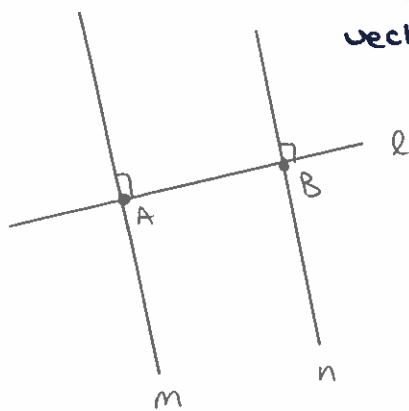
$\Rightarrow \text{Rot}_\psi \circ \text{Rot}_\phi = r_n \circ r_m \circ r_m \circ r_l = r_n \circ r_l$ ,

and  $n$  and  $l$  meet at  $O$  forming angle  $\frac{1}{2}(\phi + \psi)$

$\Rightarrow \text{Rot}_\psi \circ \text{Rot}_\phi = \text{Rot}_{\phi + \psi}$ , a rotation.

(c) Let  $A$  and  $B$  be two different points. Let  $R_1 = \text{Rot}_{A, 180}$ ,  $R_2 = \text{Rot}_{B, 180}$ .

Prove that  $R_2 \circ R_1$  is a translation, and identify the displacement vector.



Let  $l = \overleftrightarrow{AB}$ .

Let  $m$  be the perpendicular bisector to  $l$  at  $A$ , and  $n$  the perpendicular bisector to  $l$  at  $B$ .

$\Rightarrow R_1 = r_l \circ r_m$ ,  $R_2 = r_n \circ r_l$ .

$\Rightarrow R_2 \circ R_1 = r_n \circ r_l \circ r_l \circ r_m = r_n \circ r_m$ ,

and  $m$  and  $n$  are parallel.

$\Rightarrow r_n \circ r_m$  is translation, with displacement vector  $2\overrightarrow{AB}$ .

(d)  $\mathcal{R} = \{\text{rotations}\}$   $\mathcal{R}_0 = \{\text{rotations about } O\}$

Is  $\mathcal{R}$  a group? Is  $\mathcal{R}_0$  a group?

•  $\mathcal{R}$  is not a group: by (c) it is not closed under composition.

•  $\mathcal{R}_0$  is a group: by (b) it is closed under composition  
by (a) it is closed under inverses.

Exercise 4:

$$G = T_{AB} \circ r_\ell, \quad \vec{AB} \neq \vec{0}, \quad \vec{AB} \parallel \ell.$$

Show that

(a) the only invariant line under  $G$  is  $\ell$ .

•  $\ell$  is clearly invariant (fixed under  $r_\ell$ , invariant under  $T_{AB}$ ).

• suppose  $m$  is an invariant line, so  $T_{AB} \circ r_\ell(m) = m$ .

$$\Rightarrow r_\ell(m) = T_{AB}^{-1}(m).$$

• translation preserves direction of lines, so  $T_{AB}^{-1}(m) \parallel m$ .

• but the only way  $r_\ell(m) \parallel m$  is if  $m \parallel \ell$ ,  $m = \ell$  or  $m \perp \ell$ .

• if  $m \parallel \ell$ ,  $T_{AB}^{-1}(m) = m$ , but  $r_\ell(m) \neq m$ . #

• if  $m \perp \ell$ ,  $T_{AB}^{-1}(m) \neq m$ , but  $r_\ell(m) = m$ . #

So the only option is  $m = \ell$ .

(b)  $G$  has no fixed points

$$\begin{aligned} \text{Note that } G^2 &= (T_{AB} \circ r_\ell) \circ (r_\ell \circ T_{AB}) \\ &= T_{2AB}. \end{aligned}$$

If  $G(P) = P$ ,  $G^2(P) = P$ , so  $P$  is also a fixed point of  $T_{2AB}$ .

But  $\vec{AB} \neq \vec{0} \Rightarrow 2\vec{AB} \neq \vec{0} \Rightarrow T_{2AB}$  has no fixed points.

$\therefore G$  has no fixed points.

Alternate approach: use coordinates (with  $\ell = x$ -axis)

$$G: (x, y) \mapsto (x+a, -y).$$