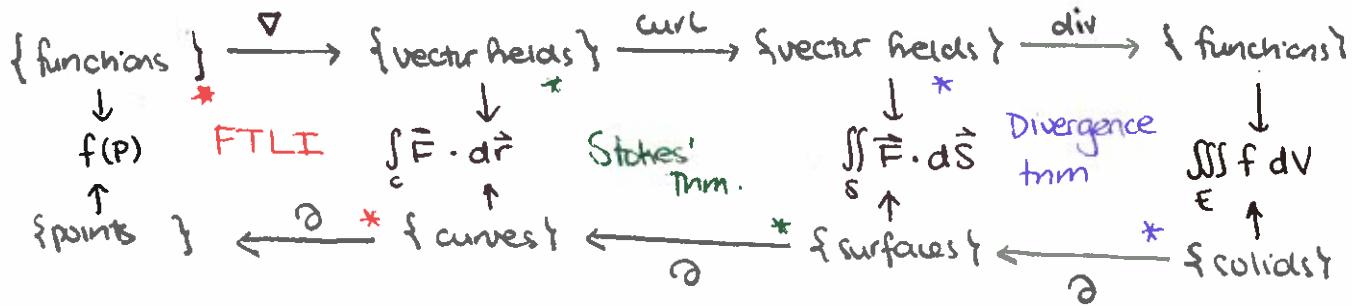


- Last time \square topology 101

- Announcements



Fundamental theorem of line integrals.

- * Start with a function f and a curve C

1) ∇ : $\int_C \nabla f \cdot d\vec{r}$

2) ∂ : $f(Q) - f(P)$



Stokes' Theorem:

- * Start with a vector field \vec{F} and a surface S .

1) curl: $\iint_S \text{curl } \vec{F} \cdot d\vec{s}$

2) ∂ : $\oint_{\partial S} \vec{F} \cdot d\vec{r}$

Divergence Theorem:

- * Start with a vector field \vec{F} and a solid E .

1) div: $\iiint_E \text{div } \vec{F} dV$

2) ∂ : $\iint_{\partial E} \vec{F} \cdot d\vec{S}$

1) Any two consecutive arrows on the top row give 0

2) Any two consecutive arrows on the bottom row give the empty set.

3) Can integrate/evaluate any column to get a number

4) Each square is a theorem

Approaches to solving problems.

40.2

$$\int_C \vec{F} \cdot d\vec{r}$$

(1) if $\vec{F} = \nabla g$, use fundamental theorem of line integrals

(2) solve directly if possible

(3) Are you in \mathbb{R}^2 or \mathbb{R}^3 ?

\mathbb{R}^2 - use Green's theorem:

Choose $D \subset \mathbb{R}^2$ so that \vec{F} is nice on D .

(a) ideal: $\partial D = \Gamma$

(b) okay: $\partial D = \Gamma_1 \cup \Gamma_2$, where $\int_{\Gamma} \vec{F} \cdot d\vec{r}$ is "easy"

\mathbb{R}^3 - use Stokes' theorem:

Find oriented surface so \vec{F} is nice on S .

(a) ideal: $\partial S = C$

(b) okay: $\partial S = C_1 \cup C_2$ and $\int_C \vec{F} \cdot d\vec{r}$ is "easy".

(4) Approximate: use $\int_C \vec{F} \cdot d\vec{r} = \int_C \vec{F} \cdot \hat{T} \cdot ds$.

$= (\text{length of } C)(\text{average value of } \vec{F} \cdot \hat{T})$.

- use Riemann sum.

$$\iint_S \vec{F} \cdot d\vec{S}$$

(1) If $\vec{F} = \operatorname{curl} \vec{G}$ is given, use Stokes' theorem.

(2) Solve directly if possible

(3) Use the divergence theorem.

• Find a solid E so that \vec{F} is nice on E

(a) ideal: $\partial E = \pm S$

(b) okay: $\partial E = \Gamma_1 \cup \Gamma_2$ and $\iint_S \vec{F} \cdot d\vec{S}$ is "easy"

(4) approximate.

What's the best way?

1) Follow instructions

2) Do the easiest problem:

- Squiggles and blobs are hard
- polygons and boxes are hard
- complicated vector fields are hard
- already parametrized surfaces

→ • "approximate" and "positive/negative/zero" are easier

(3) Do steps in order.

* Don't be afraid to waste a little time, but don't waste too much time.