

Yangians and their representations

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Preliminary course outline

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Lecture 1. History and background, R -matrix definition, basic structural results in type A .

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Lecture 4. Yangians in arbitrary types, their representations and applications.

References

References

V. Chari and A. Pressley, A guide to quantum groups (1994),
Chapter 12.

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A. Molev, Yangians and classical Lie algebras (2007),
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History and background: Yang–Baxter equation

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Cairns, Australia, 2010

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In this case we say that R is an **R -matrix**.

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$$R_{12}(u) R_{13}(u + v) R_{23}(v) = R_{23}(v) R_{13}(u + v) R_{12}(u),$$

or multiplicative,

$$R_{12}(u) R_{13}(uv) R_{23}(v) = R_{23}(v) R_{13}(uv) R_{12}(u).$$

In the theory of integrable lattice models, one considers the
monodromy matrices

$$T_0(u) = R_{01}(u + c_1) \dots R_{0n}(u + c_n), \quad c_i \in \mathbb{C},$$

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in the vector space $V \otimes V^{\otimes n}$.

By taking trace over the 0-th copy of V , we get the **transfer matrix** $\text{tr} T(u)$.

The Yang–Baxter equation implies

$$R_{00'}(u - v) T_0(u) T_{0'}(v) = T_{0'}(v) T_0(u) R_{00'}(u - v)$$

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By taking trace over the copies of V labelled by 0 and $0'$, we get

$$[\mathrm{tr} T(u), \mathrm{tr} T(v)] = 0.$$

The transfer matrices $\text{tr } T(u)$ thus provide a commuting family of operators in $V^{\otimes n}$. One would like to find their eigenvalues and eigenvectors.

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The models with particular R -matrices were studied, the techniques of **Bethe ansatz** was used.

These include the XXX , XXZ and XYZ models; see book by [R. Baxter 1982].

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Another interpretation of the Yang–Baxter equation — factorization property of scattering matrices; originated in [C. N. Yang 1967].

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emergence of new algebraic structures.

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The key step is to regard the monodromy matrix relation as
a definition: review paper by **P. Kulish and E. Sklyanin 1982**.

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The relation

$$R_{12}(u - v) T_1(u) T_2(v) = T_2(v) T_1(u) R_{12}(u - v),$$

which is now known as the **RTT-relation**, defines an abstract
algebra whose generators are matrix elements of $T(u)$.

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The function

$$R(u) = u1 + P$$

is a solution of the Yang–Baxter equation, known as the **Yang R -matrix**.

Take $\dim V = 2$ so that

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we get the relations in terms of the matrix entries. In particular,

$$[A(u), A(v)] = 0,$$

$$(u-v) [A(u), B(v)] = A(v) B(u) - A(u) B(v),$$

$$(u-v) [B(u), C(v)] = D(v) A(u) - D(u) A(v), \quad \text{etc.}$$

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These elements lie in the center of the algebra.

Drinfeld's definition

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The matrix elements of $T(u)$ should be understood as formal series in u^{-1} , like

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etc., so that the RTT relation defines an algebra with countably many generators.

This leads to the definition of the **Yangian** $Y(\mathfrak{g}_2)$

[V. Drinfeld 1985]. The name was given in honor of C. N. Yang.

The Yangians $Y(\mathfrak{a})$ were defined for all simple Lie algebras \mathfrak{a} .

Yangian for \mathfrak{gl}_N

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Definition.

The **Yangian** for \mathfrak{gl}_N is the associative algebra over \mathbb{C} with countably many generators $t_{ij}^{(1)}, t_{ij}^{(2)}, \dots$ where $i, j = 1, \dots, N$, and the defining relations

$$[t_{ij}^{(r+1)}, t_{kl}^{(s)}] - [t_{ij}^{(r)}, t_{kl}^{(s+1)}] = t_{kj}^{(r)} t_{il}^{(s)} - t_{kj}^{(s)} t_{il}^{(r)},$$

where $r, s = 0, 1, \dots$ and $t_{ij}^{(0)} = \delta_{ij}$.

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where $r, s = 0, 1, \dots$ and $t_{ij}^{(0)} = \delta_{ij}$.

This algebra is denoted by $Y(\mathfrak{gl}_N)$.

Introduce the formal generating series

$$t_{ij}(u) = \delta_{ij} + t_{ij}^{(1)}u^{-1} + t_{ij}^{(2)}u^{-2} + \cdots \in Y(\mathfrak{gl}_N)[[u^{-1}]].$$

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The defining relations take the form

$$(u - v) [t_{ij}(u), t_{kl}(v)] = t_{kj}(u) t_{il}(v) - t_{kj}(v) t_{il}(u) :$$

equate the coefficients of $u^{-r}v^{-s}$.

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Proposition. The defining relations can be written equivalently as

$$[t_{ij}^{(r)}, t_{kl}^{(s)}] = \sum_{a=1}^{\min\{r,s\}} \left(t_{kj}^{(a-1)} t_{il}^{(r+s-a)} - t_{kj}^{(r+s-a)} t_{il}^{(a-1)} \right).$$

Proof. Write the relations in the form

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Expand

$$\frac{1}{u-v} = \sum_{p=1}^{\infty} u^{-p} v^{p-1}.$$

Taking the coefficients of $u^{-r} v^{-s}$ on both sides gives

$$[t_{ij}^{(r)}, t_{kl}^{(s)}] = \sum_{a=1}^r \left(t_{kj}^{(a-1)} t_{il}^{(r+s-a)} - t_{kj}^{(r+s-a)} t_{il}^{(a-1)} \right).$$

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This agrees with the formula in the case $r \leq s$. If $r > s$ then

$$\sum_{a=s+1}^r \left(t_{kj}^{(a-1)} t_{il}^{(r+s-a)} - t_{kj}^{(r+s-a)} t_{il}^{(a-1)} \right) = 0. \quad \square$$

Introduce the permutation operator

$$P = \sum_{i,j=1}^N e_{ij} \otimes e_{ji} \in \text{End } \mathbb{C}^N \otimes \text{End } \mathbb{C}^N,$$

where $e_{ij} \in \text{End } \mathbb{C}^N$ are the standard matrix units.

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The rational function

$$R(u) = 1 - P u^{-1}$$

with values in $\text{End } \mathbb{C}^N \otimes \text{End } \mathbb{C}^N$ is called the **Yang R -matrix**.

Proposition.

The Yang R -matrix is a solution of the Yang–Baxter equation

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Proof. Multiplying both sides by $uv(u + v)$ we come to verify the identity

$$(u - P_{12})(u + v - P_{13})(v - P_{23}) = (v - P_{23})(u + v - P_{13})(u - P_{12}).$$

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It is immediate from the relations in the group algebra $\mathbb{C}[\mathfrak{S}_3]$.

For instance, for the constant term we have

$$P_{12} P_{13} P_{23} = P_{23} P_{13} P_{12}.$$

□

Matrix form of the defining relations

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Introduce the $N \times N$ matrix $T(u)$ whose ij -th entry is the series $t_{ij}(u)$:

$$T(u) = \begin{bmatrix} t_{11}(u) & t_{12}(u) & \dots & t_{1N}(u) \\ t_{21}(u) & t_{22}(u) & \dots & t_{2N}(u) \\ \dots & \dots & \dots & \dots \\ t_{N1}(u) & t_{N2}(u) & \dots & t_{NN}(u) \end{bmatrix} .$$

Note that for any algebra \mathcal{A} we have the isomorphism

$$\text{Mat}_N(\mathcal{A}) \cong \text{End } \mathbb{C}^N \otimes \mathcal{A}.$$

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We will regard $T(u)$ as an element of the algebra

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and introduce its elements by

$$T_1(u) = \sum_{i,j=1}^N e_{ij} \otimes 1 \otimes t_{ij}(u) \quad \text{and} \quad T_2(u) = \sum_{i,j=1}^N 1 \otimes e_{ij} \otimes t_{ij}(u).$$

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Proposition.

The defining relations of the Yangian $Y(\mathfrak{gl}_N)$ can be written in the form of *RTT*-relation

$$R(u - v) T_1(u) T_2(v) = T_2(v) T_1(u) R(u - v).$$

Proof. Recalling the definition of the Yang R -matrix, we can write the relation in the form

$$[T_1(u), T_2(v)] = \frac{1}{u - v} (P T_1(u) T_2(v) - T_2(v) T_1(u) P).$$

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to get

$$[t_{ij}(u), t_{kl}(v)] = \frac{1}{u-v} (t_{kj}(u) t_{il}(v) - t_{kj}(v) t_{il}(u)). \quad \square$$

Connection with $U(\mathfrak{gl}_N)$

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Proposition. The assignment

$$\text{ev} : t_{ij}^{(1)} \mapsto E_{ij} \quad \text{and} \quad t_{ij}^{(r)} \rightarrow 0 \quad \text{for} \quad r \geq 2,$$

defines an epimorphism $Y(\mathfrak{gl}_N) \rightarrow U(\mathfrak{gl}_N)$.

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defines an epimorphism $Y(\mathfrak{gl}_N) \rightarrow U(\mathfrak{gl}_N)$. Equivalently,

$$\text{ev} : t_{ij}(u) \mapsto \delta_{ij} + E_{ij} u^{-1}.$$

Proof. Introduce the matrix

$$E = \begin{bmatrix} E_{11} & E_{12} & \dots & E_{1N} \\ E_{21} & E_{22} & \dots & E_{2N} \\ \dots & \dots & \dots & \dots \\ E_{N1} & E_{N2} & \dots & E_{NN} \end{bmatrix}$$

with entries in $U(\mathfrak{gl}_N)$.

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by setting

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where

$$E_1 = \sum_{i,j=1}^N e_{ij} \otimes 1 \otimes E_{ij} \quad \text{and} \quad E_2 = \sum_{i,j=1}^N 1 \otimes e_{ij} \otimes E_{ij}.$$

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We need to verify that

$$\begin{aligned} & [1 + E_1 u^{-1}, 1 + E_2 v^{-1}] \\ &= \frac{1}{u - v} \left(P(1 + E_1 u^{-1})(1 + E_2 v^{-1}) \right. \\ & \quad \left. - (1 + E_2 v^{-1})(1 + E_1 u^{-1})P \right). \end{aligned}$$

Hence the map ev is written in the matrix form as

$$ev : T(u) \mapsto 1 + E u^{-1}.$$

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Note the relations

$$PE_1 = E_2P \quad \text{and} \quad PE_2 = E_1P.$$

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$$[E_1, E_2] = \frac{1}{u - v} \left((u + E_2)(v + E_1)P - (v + E_2)(u + E_1)P \right).$$

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The map $ev : Y(\mathfrak{gl}_N) \rightarrow U(\mathfrak{gl}_N)$ is known as the **evaluation homomorphism**.

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Proposition. The assignment

$$\iota : E_{ij} \mapsto t_{ij}^{(1)}$$

defines an embedding $U(\mathfrak{gl}_N) \hookrightarrow Y(\mathfrak{gl}_N)$.

Proof. Recall the defining relations,

$$[t_{ij}^{(r)}, t_{kl}^{(s)}] = \sum_{a=1}^{\min\{r,s\}} \left(t_{kj}^{(a-1)} t_{il}^{(r+s-a)} - t_{kj}^{(r+s-a)} t_{il}^{(a-1)} \right),$$

and take $r = s = 1$, showing that the map is a homomorphism.

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Note that the composition $\text{ev} \circ \iota$ of the map $\iota : U(\mathfrak{gl}_N) \hookrightarrow Y(\mathfrak{gl}_N)$ and the evaluation homomorphism $\text{ev} : Y(\mathfrak{gl}_N) \rightarrow U(\mathfrak{gl}_N)$ is the identity map on $U(\mathfrak{gl}_N)$.

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We thus may regard $U(\mathfrak{gl}_N)$ as a subalgebra of $Y(\mathfrak{gl}_N)$.

Symmetries of $Y(\mathfrak{gl}_N)$

Let $f(u)$ be a formal power series in u^{-1} of the form

$$f(u) = 1 + f_1 u^{-1} + f_2 u^{-2} + \cdots \in \mathbb{C}[[u^{-1}]].$$

Let $c \in \mathbb{C}$ and let B be any invertible complex $N \times N$ matrix.

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Proposition. Each of the mappings

$$T(u) \mapsto f(u) T(u),$$

$$T(u) \mapsto T(u + c),$$

$$T(u) \mapsto B T(u) B^{-1}$$

defines an automorphism of $Y(\mathfrak{gl}_N)$.

Proof. We need to verify that each map preserves the defining relations and is invertible.

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It is clear that the maps $T(u) \mapsto f(u) T(u)$ and $T(u) \mapsto T(u + c)$ preserve the RTT relation

$$R(u - v) T_1(u) T_2(v) = T_2(v) T_1(u) R(u - v).$$

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because

$$A_1 A_2 = A_2 A_1 \quad \text{and} \quad P A_1 A_2 = A_2 A_1 P.$$

This implies that the matrices $A T(u)$ and $T(u) A$ also satisfy the *RTT* relation:

$$R(u - v) A_1 T_1(u) A_2 T_2(v) = R(u - v) A_1 A_2 T_1(u) T_2(v)$$

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All three homomorphisms are obviously invertible. □

Proposition. Each of the mappings

$$\sigma_N : T(u) \mapsto T(-u),$$

$$t : T(u) \mapsto T^t(u),$$

$$S : T(u) \mapsto T^{-1}(u)$$

defines an anti-automorphism of $Y(\mathfrak{gl}_N)$.

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Proof. The images $t_{ij}^\circ(u)$ of the series $t_{ij}(u)$ under any anti-automorphism of $Y(\mathfrak{gl}_N)$ must satisfy the defining relations with the opposite multiplication:

$$(u - v) [t_{ij}^\circ(u), t_{kl}^\circ(v)] = t_{il}^\circ(u)t_{kj}^\circ(v) - t_{il}^\circ(v)t_{kj}^\circ(u).$$

These relations can be equivalently written in the matrix form:

$$R(u - v) T_2^\circ(v) T_1^\circ(u) = T_1^\circ(u) T_2^\circ(v) R(u - v),$$

where $T^\circ(u)$ is the $N \times N$ matrix whose ij -th entry is $t_{ij}^\circ(u)$.

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The relation

$$R(u - v) T_2(-v) T_1(-u) = T_1(-u) T_2(-v) R(u - v)$$

follows from the RTT relation by conjugating both sides by P and then replacing (u, v) by $(-v, -u)$.

Lemma. Let \mathcal{A} be an associative algebra.

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Suppose that two elements

$$X = \sum_{i,j=1}^N e_{ij} \otimes X_{ij} \quad \text{and} \quad Y = \sum_{i,j=1}^N e_{ij} \otimes Y_{ij}$$

of the algebra $\text{End } \mathbb{C}^N \otimes \mathcal{A}$ satisfy the property

$$X_{ij} Y_{kl} = Y_{kl} X_{ij} \quad \text{for all } i, j, k, l.$$

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of the algebra $\text{End } \mathbb{C}^N \otimes \mathcal{A}$ satisfy the property

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Then

$$(XY)^t = Y^t X^t.$$

Proof. We have

$$Y^t X^t = \sum_{i,j,k,l=1}^N e_{lk} e_{ji} \otimes Y_{kl} X_{ij} = \sum_{i,j,l=1}^N e_{li} \otimes Y_{jl} X_{ij}.$$

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On the other hand,

$$XY = \sum_{i,j,k,l=1}^N e_{ij} e_{kl} \otimes X_{ij} Y_{kl} = \sum_{i,j,l=1}^N e_{il} \otimes Y_{jl} X_{ij},$$

so that the application of the transposition yields $Y^t X^t$. □

Apply the partial transposition operator t_1 to both sides of the RTT relation

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By the Lemma, we get

$$T_1^t(u) R^t(u - v) T_2(v) = T_2(v) R^t(u - v) T_1^t(u).$$

Since $R(u - v)$ is stable under the composition $t_2 \circ t_1$,

Since $R(u - v)$ is stable under the composition $t_2 \circ t_1$, applying t_2 we get

$$T_1^t(u) T_2^t(v) R(u - v) = R(u - v) T_2^t(v) T_1^t(u),$$

showing that t is an anti-automorphism.

Finally, observe that the relation

$$R(u - v) T_2^{-1}(v) T_1^{-1}(u) = T_1^{-1}(u) T_2^{-1}(v) R(u - v)$$

is equivalent to the RTT relation so that S is an anti-homomorphism.

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Note now that the mappings σ_N and t are involutive and so these anti-homomorphisms are bijective.

Remark. The anti-homomorphism S is **not** involutive.

To complete the proof, take the composition of the anti-homomorphisms σ_N and S to get the homomorphism

$$\omega_N : T(u) \mapsto T^{-1}(-u).$$

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$$\omega_N(T(u)) \cdot T(-u) = 1$$

to get

$$\omega_N^2(T(u)) \cdot T^{-1}(u) = 1.$$

So $\omega_N^2 = 1$ and S is bijective. □

Poincaré–Birkhoff–Witt theorem

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Proof. Introduce the ascending filtration on $Y(\mathfrak{gl}_N)$ by $\deg t_{ij}^{(r)} = r$. By the defining relations

$$[t_{ij}^{(r)}, t_{kl}^{(s)}] = \sum_{a=1}^{\min\{r,s\}} \left(t_{kj}^{(a-1)} t_{il}^{(r+s-a)} - t_{kj}^{(r+s-a)} t_{il}^{(a-1)} \right),$$

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the corresponding graded algebra $\text{gr } Y(\mathfrak{gl}_N)$ is commutative.

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Denote by $\bar{t}_{ij}^{(r)}$ the image of $t_{ij}^{(r)}$ in the r -th component of $\text{gr } Y(\mathfrak{gl}_N)$. It will be sufficient to show that the elements $\bar{t}_{ij}^{(r)}$ are algebraically independent.

By the defining relations, for any $M \geq 0$ there is a homomorphism

$$\iota_M : Y(\mathfrak{gl}_N) \rightarrow Y(\mathfrak{gl}_{N+M}),$$

such that $t_{ij}^{(r)} \mapsto t_{ij}^{(r)}$.

By the defining relations, for any $M \geq 0$ there is a homomorphism

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such that $t_{ij}^{(r)} \mapsto t_{ij}^{(r)}$. Take the composition

$$\zeta_M = \text{ev}_{N+M} \circ \omega_{N+M} \circ \iota_M.$$

The automorphism ω_{N+M} of the algebra $Y(\mathfrak{gl}_{N+M})$ is defined by

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$$\text{ev}_{N+M} : Y(\mathfrak{gl}_{N+M}) \rightarrow U(\mathfrak{gl}_{N+M})$$

is the evaluation homomorphism,

$$T(u) \mapsto 1 + E u^{-1}.$$

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we have

$$\zeta_M : t_{ij}^{(r)} \mapsto (E^r)_{ij},$$

and E is the $(N + M) \times (N + M)$ matrix whose ij -th entry is E_{ij} .

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Passing to the graded algebras, we get the homomorphism

$$\bar{\zeta}_M : \text{gr } Y(\mathfrak{gl}_N) \rightarrow S(\mathfrak{gl}_{N+M}),$$

where $S(\mathfrak{gl}_{N+M})$ is the symmetric algebra of \mathfrak{gl}_{N+M} .

The image of $\bar{t}_{ij}^{(r)}$ under $\bar{\zeta}_M$ is the polynomial $p_{ij}^{(r)}$ such that

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For a large enough M , choose disjoint subsets

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and let $y_{ij}^{(r)}$ be independent parameters.

Now take

$$X = \sum_{i,j=1}^N \sum_{r=1}^R \left(e_{ia_1} + e_{a_1a_2} + \cdots + e_{a_{r-2}a_{r-1}} + y_{ij}^{(r)} e_{a_{r-1}j} \right).$$

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Hence, these polynomials are algebraically independent. \square

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(the **coassociativity** of Δ), and

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A **bialgebra** is an associative unital algebra A equipped with a coalgebra structure, such that Δ and ε are algebra homomorphisms.

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A **bialgebra** is an associative unital algebra A equipped with a coalgebra structure, such that Δ and ε are algebra homomorphisms.

In particular, $\Delta(1) = 1 \otimes 1$ and $\varepsilon(1) = 1$.

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 A \otimes A & \xrightarrow{S \otimes \text{id}} & A \otimes A \\
 \Delta \uparrow & & \downarrow \mu \\
 A & \xrightarrow{\delta \circ \varepsilon} & A
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where $\mu : A \otimes A \rightarrow A$ is the algebra multiplication and $\delta : \mathbb{C} \rightarrow A$ is the unit map of the algebra A ; that is, $\delta(c) = c \cdot 1$ for any $c \in \mathbb{C}$.